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Research Article

Scaffold assembly based on genome rearrangement analysis

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ABSTRACT

Advances in DNA sequencing technology over the past decade have increased the volume of raw sequenced genomic data available for further assembly and analysis. While there exist many algorithms for assembly of sequenced genomic material, they often experience difficulties in constructing complete genomic sequences. Instead, they produce long genomic subsequences (*scaffolds*), which then become a subject to scaffold assembly aimed at reconstruction of their order along genome chromosomes. The balance between reliability and cost for scaffold assembly is not there just yet, which inspires one to seek for new approaches to address this problem. We present a new method for scaffold assembly based on the analysis of gene orders and genome rearrangements in multiple related genomes (some or even all of which may be fragmented). Evaluation of the proposed method on artificially fragmented mammalian genomes demonstrates its high reliability. We also apply our method for incomplete anophelinae genomes, which expose high fragmentation, and further validate the assembly results with referenced-based scaffolding. While the two methods demonstrate consistent results, the proposed method is able to identify more assembly points than the reference-based scaffolding.

1. Background

Genome sequencing technology has evolved over time, increasing availability of sequenced genomic data. Modern sequencers are able to identify only short subsequences (*reads*) in the supplied genomic material, which then become an input to genome assembly algorithms aimed at reconstruction of the complete genome. Such reconstruction is possible (but not guaranteed) only if each genomic region is covered by sufficiently many reads. Lack of comprehensive coverage (particularly severe in single-cell sequencing Chitsaz et al. (2011), Nikolenko et al. (2013)) and presence of long similar subsequences (*repeats*) in genomes pose major obstacles for existing assembly algorithms. They therefore often are able to reliably reconstruct only long subsequences of the genome (interspaced with low-coverage regions and repeats), called *scaffolds*.

The challenge of reconstructing a complete genomic sequence from scaffolds is known as the *scaffolds assembly* problem. It is often addressed technologically by generating so-called long-jump libraries Talkowski et al. (2012), Collins and Weissman (1984) or by using a related complete genome as a reference. Unfortunately, the technological solution may be expensive and inaccurate Hunt et al. (2014), while the reference-based approach is obfuscated with structural variations across the genomes Feuk et al. (2006).

In the current study, we assume that the constructed scaffolds are accurate and long enough to allow identification of orthologous genes. The scaffolds then can be represented as ordered sequences of genes and we pose the scaffolds assembly problem as the reconstruction of the global gene order (along genome chromosomes) from the gene sub-orders defined by the scaffolds. We view such gene sub-orders as the result of both evolutionary events and technological fragmentation in the genome. Evolutionary events that change gene orders are *genome rearrangements*, most common of which are *reversals*, *fusions*, *fissions*, and *translocations*. Technological fragmentation can be modeled by artificial "fissions" that break genomic chromosomes into scaffolds. Scaffold assembly can therefore be reduced to the search for "fusions" that revert technological "fissions" and glue scaffolds back into chromosomes. This observation inspires us to employ the genome rearrangement analysis techniques for scaffolding purposes.

Rearrangement analysis of multiple genomes relies on the concept of the breakpoint graph. While traditionally the breakpoint graph is constructed for complete genomes, it can also be constructed for fragmented genomes, where we treat scaffolds as "chromosomes". We will demonstrate that the breakpoint graph of multiple genomes possesses an important property that its connected components are robust with respect to genome fragmentation. In other words, connected components of the

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[1] See Appendix A.

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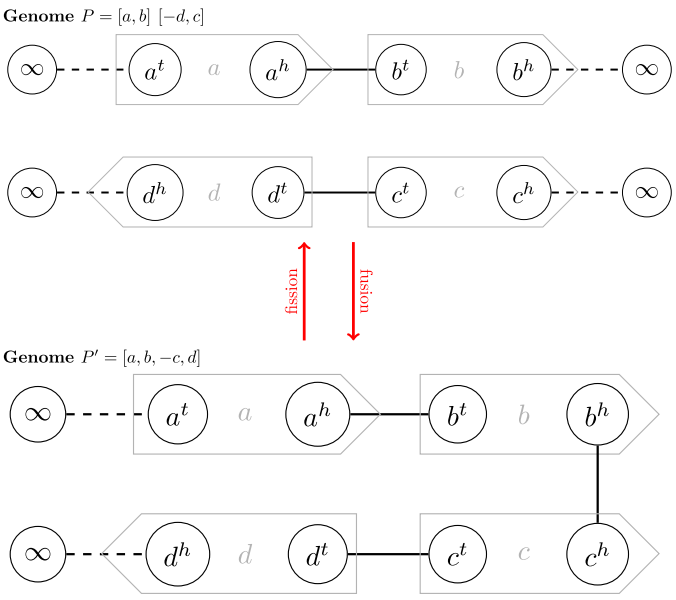


Fig. 1. Fusion/fission operations between the genome graphs of two-chromosomal genome $P = [a, b]\,[-d, c]$ and unichromosomal genome $P' = [a, b, -c, d]$, where regular and irregular edges are represented as solid and dashed, respectively. Grey boxes enclose pairs of vertices representing genes.

breakpoint graph mostly retain information about the complete genomes, even when the breakpoint graph is constructed on their scaffolds. We will show how to utilize connected components of the breakpoint graph for the scaffold assembly of fragmented genomes.

The paper is organized as follows. In Section 2, we provide background information about breakpoint graphs and genome rearrangements, discuss connected components of breakpoint graphs with respect to genome fragmentation, and describe our scaffold assembly algorithm. In Section 3, we evaluate our proposed algorithm on both simulated and real data. We summarize and discuss the paper results in Section 4.

2. Methods

2.1. Genome and breakpoint graphs

We start with defining a graph representation for a single genome, which may consist of multiple chromosomes and/or scaffolds commonly referred to as *fragments*. We represent each fragment with n genes as an undirected graph on $2 \cdot n$ *regular* vertices representing gene extremities and several *irregular* vertices, labeled by ∞, encoding fragment ends (telomeres, if a fragment is a chromosome). A gene a is represented by two regular vertices labeled as a^t and a^h denoting its *tail* and *head* extremities, respectively. Vertices corresponding to extremities of adjacent genes are connected by *regular* edges. Each vertex corresponding to a gene extremity at a fragment end is connected to an irregular vertex with an *irregular* edge. The *genome graph* of a genome is formed by the graph representing its fragments.

We remark that a single genome rearrangement affects the genome graph as follows: a pair of edges are removed and a new pair of edges on the same four vertices is created (Fig. 1). Genome rearrangements are therefore often modeled as DCJ Yancopoulos et al. (2005) or 2-break Alekseyev and Pevzner (2008) operations on graphs.

The *breakpoint graph* of k genomes composed of the same ℓ genes consists of $2 \cdot \ell$ regular vertices (representing gene extremities), a number of irregular vertices (representing fragment ends) and undirected edges of k colors (one color reserved for each of the genomes) encoding adjacencies between genes and/or fragment ends in the genomes. The breakpoint graph can be viewed as the superposition of k genome graphs of individual genomes (Fig. 2). All edges connecting a pair of vertices in the breakpoint graph form a *multiedge*, whose *multicolor* is the set of individual colors in the multiedge[3] (e.g., in Fig. 2 vertices a^h and b^t are connected by a multiedge of the red–black multicolor).

We remark that traditionally breakpoint graphs are constructed on synteny blocks whose endpoints represent *breakpoints* (thus the name) in the genomes. In contrast, we construct the breakpoint graph directly on genes, whose extremities may or may not form breakpoints. Such graph therefore can contain *trivial multiedges* formed by parallel edges of all colors, which correspond to gene adjacencies shared across all the genomes and would be hidden within synteny blocks. Clearly, each trivial multiedge in the breakpoint graph forms its own connected component, which we also call *trivial*.

2.2. Connected components and fragmentation

Under a *connected component* in the breakpoint graph we will understand any largest set of regular vertices such that any two of them are connected by a path consisting of regular edges of any colors. The connected components form a partition of the regular vertices. We will show that this partition is robust with respect to fragmentation of the genomes. Namely, we observe that the connected components of the breakpoint graph of multiple genomes are strongly connected and can be hardly broken by technological "fissions". To support this observation, we applied a number of random fissions[4] to six complete mammalian genomes and analyzed how such fissions affected the connected components of the breakpoint graph.

Using Ensembl BioMart tool Kasprzyk (2011), we obtained the following six complete mammalian genomes and pairwise orthologous gene mappings between them: *Homo sapiens* (GRCh38), *Mus musculus* (GRCm38.p2), *Rattus norvegicus* (Rnor_5.0), *Canis familiaris* (CanFam3.1), *Macaca mulatta* (MMUL_1.0), and *Pan troglodytes* (CHIMP2.1.4). From the orthologous gene mappings, we constructed gene families and filtered some of them so that each genome was represented as sequences of the same 11816 genes, each appearing in a single copy.

In order to determine how robustness of the connected components depends on the number of genomes, we analyzed different subsets of mammalian genomes of various sizes from 3 to all 6. For each subset of size ℓ, we considered all possible combinations of ℓ mammalian genomes and constructed their breakpoint graph. After the same number of random fissions[5] was applied to every genome, we computed the averaged number of nontrivial connected components in the breakpoint graphs.

The results in Fig. 3 demonstrate that as the number of genomes grows, random fissions are less likely to break connected components into smaller ones. In other words, most connected components in the breakpoint graph of fragmented genomes are likely not affected by random fissions and thus represent connected components also in the breakpoint graph of complete genomes. We will employ this robustness property of the connected components and use them to guide our scaffolding algorithm.

[3] Each regular vertex may be adjacent to at most one irregular vertex (e.g., in Fig. 2 the vertex a^t is connected to a single irregular vertex with red, black, and blue edges forming the red–black–blue mutiedge (a^t, ∞)).

[4] Unfortunately we do not have information about the actual mechanism of fragmentation of a genome into scaffolds.

[5] A random fission operation uniformly selects a regular edge in the genome graph performs a fission on this edge (Fig. 1).

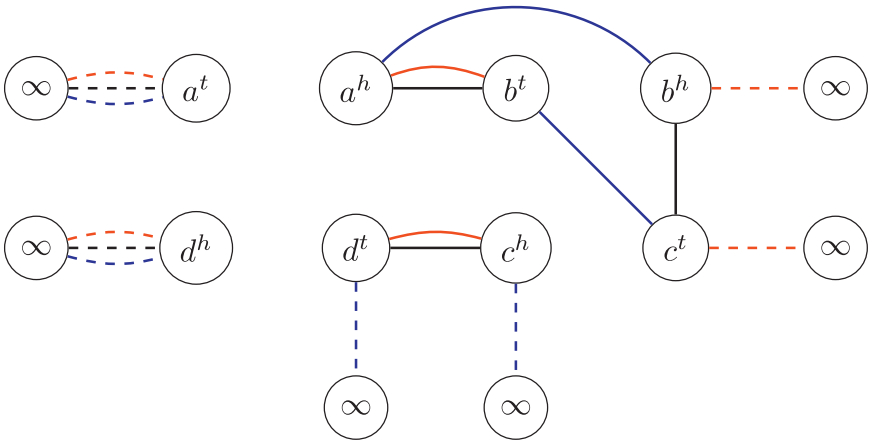


Fig. 2. Breakpoint graph $\mathbb{BG}$ of genomes $A = [a, b, c, d]$ (black edges), $B = [a, b][c, d]$ (red edges), and $C = [a, -b, c][d]$ (blue edges). Regular edges in each genome are shown as solid, while irregular edges are shown as dashed.

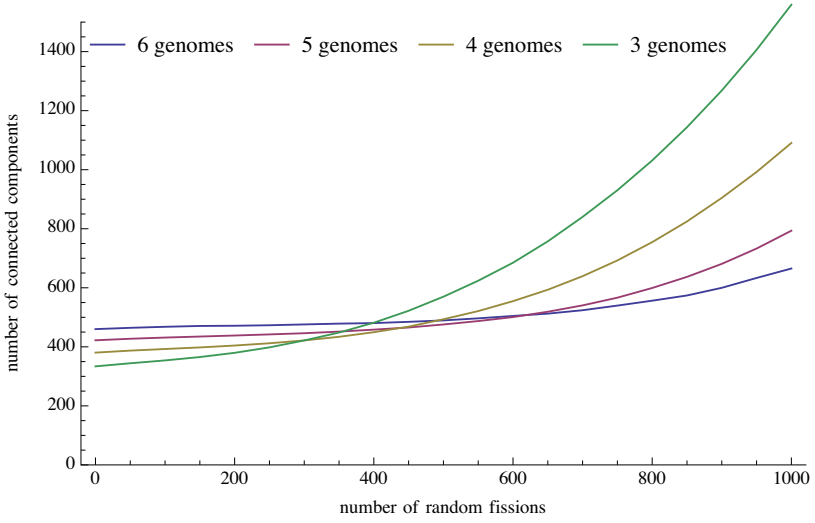


Fig. 3. Averaged number of connected components in the breakpoint graphs of multiple mammalian genomes fragmented by random "fissions". Statistics for groups of 3, 4, 5, and 6 genomes is shown in green, brown, purple, and blue, respectively. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

2.3. Scaffold assembly algorithm

Our scaffold assembly algorithm takes as an input a set of fragmented genomes, whose scaffolds are represented as sequences of genes. In the current study, we focus only on gene families that are present in each genome exactly once.

The first step of our algorithm is a construction of the breakpoint graph $\mathbb{BG}$ of the given genomes.

From the breakpoint graph perspective, scaffold assembly corresponds performing "fusions" in $\mathbb{BG}$, i.e., adding new regular edges (*assembly edges*) connecting vertices that represent scaffold ends. Since the connected components in the breakpoint graph are robust with respect to genome fragmentation, our algorithm adds assembly edges only within existing connected components and thus preserves them. So the second step of our algorithm identifies pairs of *matching vertices* that will then be connected by assembly edges (Fig. 4). Namely, vertices $x, y : x \neq y$ form a matching pair in genome P if they satisfy each of the following conditions:

connectivity: x and y belong to the same connected component X of $\mathbb{BG}$;

extremity: there are multiedges (x, ∞) and (y, ∞) of multicolor $\{P\}$ in $\mathbb{BG}$;

uniqueness: there is no vertex $z \in X$, $z \neq x$, $z \neq y$ such that the multiedge (z, ∞) has multicolor $\{P\}$; in other words, there are exactly two irregular edges of multicolor $\{P\}$ in X: (x, ∞) and (y, ∞).

```
input  : breakpoint graph 𝔹𝔾 on set G of k genomes
output: list of triples of (x, y, P) where x and y is a matching pair in genome P
result ← empty list;
ccs ← connected components (sets of vertices) of 𝔹𝔾 on regular edges of all colors;
foreach cc in ccs do
    foreach genome P in G do
        ies ← all irregular multiedges of multicolor {P} connecting vertices from cc;
        if |ies| = 2 then
            v1 ← regular vertex from first edge in ies;
            v2 ← regular vertex from second edge in ies;
            if there is edge (v1, v2) in 𝔹𝔾 then
                append (v1, v2, P) to result;
            end
        end
    end
end
return result;
```

Fig. 4. Pseudocode for identification of matching pairs of vertices.

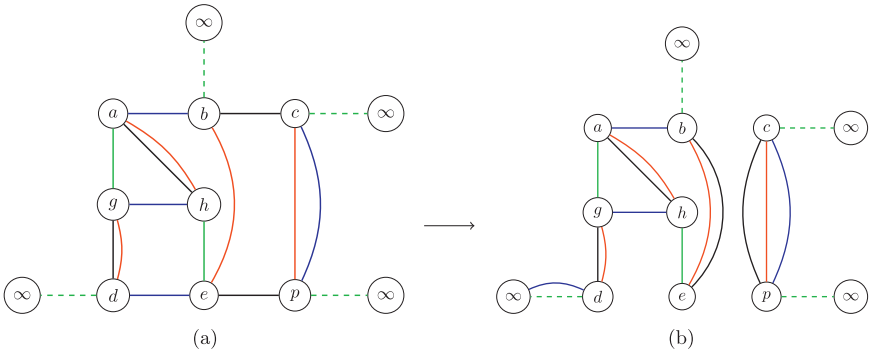


Fig. 5. Left panel: A connected component of the breakpoint graph of blue, black, red and green genomes. In this component the green genome has four irregular edges that correspond to fragment ends: (b, ∞), (c, ∞), (d, ∞), and (p, ∞). Since its endpoints b, c, p do not satisfy the uniqueness property, while endpoint d does not satisfy the extrimity property, our algorithm is not able to assemble any of corresponding fragments in the green genome. **Right panel:** A possible refinement of the connected component with MGRA with a genome rearrangement in the *black* genome. It results in a split of the connected component into two, which makes vertices c and p obtain the uniqueness property with respect to the green genome.

reliability: there exists a multiedge (x, y) (of any multicolor) in $\mathbb{BG}$.

The **connectivity** condition preserves connected components in the breakpoint graph. The **extremity** condition ensures that each of x, y represents a scaffold end in the genome P but not in any other genome.[6] The **uniqueness** condition ensures that there is a unique way to create an assembly edge for genome P inside the connected component X: if there is another multiedge (z, ∞) of multicolor $\{P\}$, it would be unclear which pair out of x, y, z to connect with an assembly edge. The **reliability** condition ensures that the new adjacency created by an assembly edge (x, y) in genome P is already present in some other genome(s).[7]

Once we obtained a list of matching vertex pairs for every genome P, we perform assembly of the corresponding fragment ends in P.

2.4. Integration with MGRA framework

We remark that our algorithm can be integrated with the MGRA framework Alekseyev and Pevzner (2009), which performs rearrangement analysis of multiple genomes, identifies reliable genome rearrangements and transforms their breakpoint graph into an *identity* breakpoint graph (of a single ancestral genome). The identity breakpoint graph consists of trivial multicycles, each forming its own connected component. In the process of this transformation MGRA can only break the connected components of the breakpoint graph into smaller ones, which can be viewed as a refinement of the original connected components. As a result, MGRA can make possible for two vertices to obtain the uniqueness property after a number of genome rearrangements (Fig. 5).

However, since the irregular edges in the breakpoint graph after a number of genome rearrangements may no longer correspond to fragment ends, the **extremity** condition does not anymore imply that x and y are fragment ends. Therefore, to integrate the scaffold assembly with MGRA, we modify the **extremity** condition to additionally test if x and y correspond to fragment ends in the genome P. By similar reasons, the **reliability** condition for vertices x, y should be tested in the original breakpoint graph. So if $\mathbb{BG}$ denotes the original breakpoint graph, while $\mathbb{BG}'$ denotes this graph after a number of genome rearrangements performed by MGRA, then a matching pair (x, y) in $\mathbb{BG}'$ should satisfy the following conditions:

connectivity': x and y belong to the same connected component X of $\mathbb{BG}'$;
extremity': there are multiedges (x, ∞) and (y, ∞) of multicolor $\{P\}$ in both $\mathbb{BG}$ and $\mathbb{BG}'$;
uniqueness': for any vertex $z \in X$ such that $z \neq x$, $z \neq y$, and the multiedge (z, ∞) in $\mathbb{BG}'$ has multicolor $\{P\}$, the multiedge (z, ∞) either is not present in $\mathbb{BG}$ or has multicolor different from $\{P\}$;
reliability': there exists a multiedge (x, y) (of any multicolor) in $\mathbb{BG}$;

Integration with MGRA allows us to obtain more matching vertices (as compared to what we can recover from the original breakpoint graph). We also take into consideration all pairs of vertices that are endpoints of fusions reported by MGRA. If such vertices correspond to fragment ends, we interpret their fusion as assembly the corresponding fragments.

3. Results and discussion

3.1. Artificially fragmented genomes

We start evaluation of the proposed scaffold assembly algorithm with running it on artificially fragmented mammalian genomes. We use the same set of six mammalian genomes and two different approaches for fragmenting them: random fragmentation and fragmentation based on repeats in the genomes. The random fragmentation allows us to overcome the lack of information about genome fragmentation mechanism. However, we may have better insight in the fragmentation model, if we assume that genome scaffolds were obtained from a conventional genome assembler having difficulties in reconstruction of the order of long DNA repeats. In this case, it becomes realistic to fragment the genomes based on locations of such repeats.

Random fragmentation.

To create instances of randomly fragmented genomes, we applied k random artificial "fissions" to each of the genomes. For each value of k, we created 10 different sets of fragmented genomes, executed our algorithm on each of the sets (both with and without MGRA integration), and reported the following normalized values (averaged over the 10 sets):

[6] Under random fragmentation, it is more likely for two genomes to share a common chromosome end than a scaffold end, which is not a chromosome end. So, if x or y is a scaffold end in two or more genomes, it is more likely for this vertex to represent a chromosome end.

[7] This condition is optional. It shall be utilized when the given genomes are closely related; however if the genomes are rather diverse, this condition may result in only small number of conservative assembly edges.

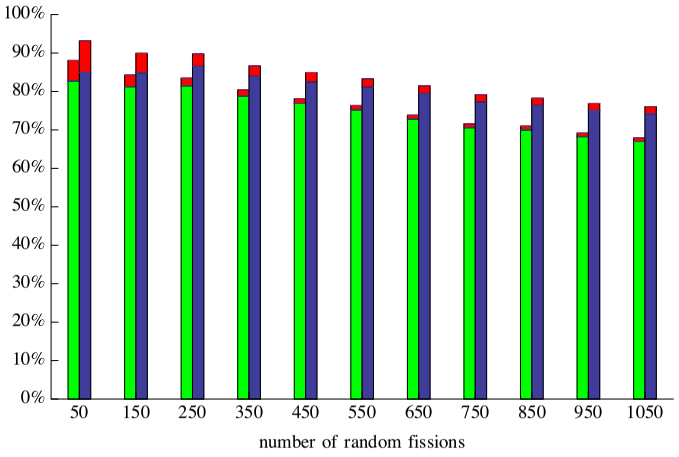


Fig. 6. Accuracy of the proposed algorithm on artificially fragmented mammalian genomes both with (blue bars) and without (green bars) integration with MGRA. For each number of random "fissions" (with step 100) applied to every genome, blue and green bars give normalized true positives, while red bar gives normalized false positives. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

- *true positive*: $|A \cap B|/|A \cup B| \cdot 100\,\%$, the percentage of assembly edges that correspond to the breakpoints of artificial "fissions".
- *false positive*: $|A \setminus B|/|A \cup B| \cdot 100\,\%$, the percentage of assembly edges that do not correspond to breakpoints of artificial "fissions" (such assembly edges may rather indicate the locations of actual fissions in mammalian evolution).

Here A is the set of pairs of fragment ends assembled by our algorithm, and B is the set of pairs of fragment ends resulted from the simulated fissions.

From the evaluation results in Fig. 6, we conclude that while our algorithm is not able to reconstruct complete genomes where fragmentation is high, it is able to reconstruct genomes almost completely, when the fragmentation is low. While the true positive rate of the assembly results decreases as fragmentation raises, the results still remain highly reliable with low false positive rate. This is not an unexpected property of our algorithm since it is based

Table 1
Statistics on the number of nonempty scaffolds in anophelinae genomes before and after gene family filtration.

Genomes	# Scaffolds	
	Before filtration	After filtration
An. gambiae	6	6
An. arabiensis	340	95
An. quadriannulatus	647	306
An. merus	1078	816
An. dirus	302	124
An. albimanus	57	39

Table 2
Statistics on the number of reported scaffold assemblies, both with and without integration with MGRA.

Genomes	# Assemblies	
	Without MGRA	Integrated with MGRA
An. gambiae	0	0
An. arabiensis	6	10
An. quadriannulatus	75	91
An. merus	466	550
An. dirus	30	45
An. albimanus	6	10

Table 3
Statistics on the number of fragments and coverage (in parenthesis) after removing all repeats of length at least L in the each of the six mammalian genomes. The column *Orth* accounts the fragments that contain at least one gene. Column *IDOrth* accounts for fragments that contain at least one non-duplicated gene. Similarly, column *UOrth* accounts for fragments that contain at least one gene present in every genome exactly once.

L	Chimpanzee			Dog			Human			Macaca			Mouse			Rat		
	Orth	IDOrth	UOrth	Orth	IDOrth	UOrth	Orth	IDOrth	UOrth	Orth	IDOrth	UOrth	Orth	IDOrth	UOrth	Orth	IDOrth	UOrth
1K	10631	6234	1636	9067	4807	1547	20318	5539	1779	10255	5345	1673	12975	4293	1597	10399	5011	1469
	(26.04)	(19.6%)	(7.7%)	(33.2%)	(24.2%)	(9.9%)	(36.8%)	(16.4%)	(6.9%)	(33.1%)	(22.8%)	(9.7%)	(38.3%)	(21.1%)	(10.1%)	(34.9%)	(27.3%)	(10.1%)
1.5K	8994	5577	1939	7150	4066	1663	16835	5256	2147	8586	4884	1943	11088	3994	1868	8742	4246	1672
	(39.01)	(30.2%)	(15.6%)	(52.1%)	(40.6%)	(21.6%)	(49.7%)	(25.9%)	(14.0%)	(47.8%)	(35.8%)	(19.4%)	(49.6%)	(30.4%)	(18.2%)	(46.4%)	(37.6%)	(18.8%)
2K	7496	4781	2016	5579	3308	1643	13797	4769	2251	6865	4213	1978	9845	3697	2053	7527	3682	1754
	(48.51)	(38.8%)	(23.8%)	(65.9%)	(53.8%)	(34.5%)	(60.6%)	(34.9%)	(21.9%)	(60.8%)	(48.5%)	(30.5%)	(56.4%)	(36.1%)	(25.2%)	(54.1%)	(44.2%)	(26.4%)
2.5K	6497	4264	2045	4389	2653	1518	11727	4425	2306	5385	3463	1848	9061	3530	2184	6651	3266	1759
	(55.9%)	(45.5%)	(30.5%)	(75.8%)	(64.2%)	(46.9%)	(67.5%)	(41.2%)	(28.2%)	(71.9%)	(59.2%)	(41.7%)	(60.5%)	(39.6%)	(29.9%)	(59.7%)	(49.1%)	(32.7%)
3K	5789	3899	2012	3605	2246	1382	10226	4121	2301	4273	2894	1682	8448	3368	2199	5997	2994	1730
	(64.9%)	(54.6%)	(38.9%)	(81.9%)	(70.9%)	(55.2%)	(72.3%)	(45.9%)	(33.1%)	(79.3%)	(67.5%)	(50.6%)	(63.5%)	(42.2%)	(33.1%)	(63.9%)	(52.4%)	(37.3%)
3.5K	5197	3589	1965	3071	1908	1258	9005	3875	2278	3368	2377	1487	7909	3204	2189	5350	2725	1661
	(69.3%6)	(58.6%)	(43.4%)	(85.6%)	(74.7%)	(61.8%)	(75.9%)	(50.3%)	(37.4%)	(84.9%)	(74.4%)	(58.6%)	(66.2%)	(44.3%)	(35.8%)	(67.9%)	(55.7%)	(41.55)
4K	4694	3292	1896	2683	1698	1175	8007	3631	2221	2635	1940	1285	7538	3125	2223	4779	2502	1601
	(73.6%)	(63.1%)	(48.1%)	(88.4%)	(78.1%)	(66.8%)	(79.2%)	(54.1%)	(41.2%)	(89.3%)	(80.1%)	(65.8%)	(68.3%)	(45.9%)	(38.1%)	(71.7%)	(58.9%)	(45.6%)

on the robustness of the connected components of the breakpoint graph. Integration with the MGRA framework further yields additional number of highly reliable fragment assemblies.

Repeat-based fragmentation.

To create instances of repeat-based fragmented genomes, we removed all repeats longer that a fixed number of basepairs (from 1 K to 4 K bp with the step of 0.5 K) and partitioned the genomes into fragments with no long repeats. We used the same set of six mammalian genomes, for which we obtained the repeats locations from RepeatMasker Smit et al. (2010) database. We performed the following three experiments:

(i) de novo assembly of multiple genomes: all six genomes are fragmented (Table 3).
(ii) assembly of multiple genomes with a single reference: all genomes, but *dog* (the only representative of the carnivore clade) are fragmented (Table 4).
(iii) assembly of a single genome with multiple references: only *dog* genome is fragmented (Table 5).

In each experiment we considered only fragments that contain genes that are present exactly once in each genome. We evaluated the proposed algorithm in the same way as in the random fragmentation experiment, both with and without MGRA integration (Fig. 7).

Experiments (i) and (ii) demonstrate that while in the presence of a reference genome our algorithm yields more true fragment adjacencies, it still performs relatively well in the case, when no reference is known. Experiment (iii) shows that our algorithm can be used as a highly reliable step for assembly of a single fragmented genome, when several complete reference genomes are known. Since DNA repeats are subject to genome rearrangements in the course of evolution, integration with MGRA yields additional true adjacencies.

3.2. Anophelinae genomes

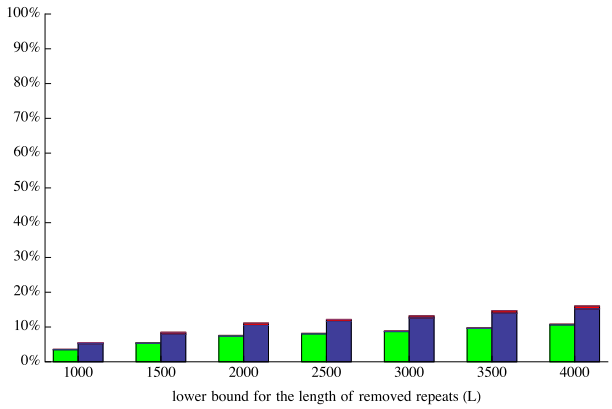
The second evaluation of our scaffold assembly algorithm was performed on highly fragmented genomes from anophelinae subfamily, followed by comparison of the results to a reference-based assembly approach. Namely, we considered six anophelinae genomes: *Anopheles gambiae*, *Anopheles arabiensis*, *An. quadriannulatus*, *An. merus*, *Anopheles dirus*, and *Anopheles albimanus*, for which we constructed gene families using orthologous gene mapping from OrthoDB Waterhouse et al. (2013). We then filtered out all gene families that are not present exactly once on each given genome, thus limiting ourselves to the case of uniform gene content across the genomes. After such filtration each genome was represented as sequences of the same 6837 genes. We remark that filtration eliminated all genes from some scaffolds and thus we exclude such scaffolds from assembly. Table 1 gives the scaffold statistics for anophelinae genomes before and after filtration.

Order and orientation of gene families in each given genome was determined from the corresponding GFF3 annotation obtained from VectorBase Megy et al. (2012), where a gene is represented by a sequence of coding exons of various length. We define the gene coordinate in a genomic fragment as the mean coordinate of all its coding exons start/end coordinates (i.e., (start + end)/2 averaged over all exons). Table 2 reports the number of scaffold assemblies obtained by the proposed algorithm.

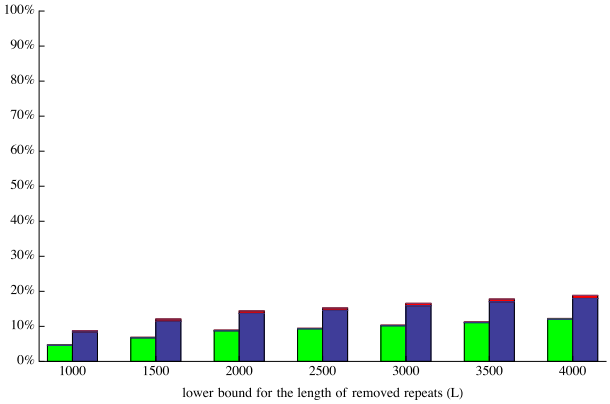
As mentioned above, we compared our assembly results to another anophelinae study (*comparison study*) led by Dr. Igor Sharakhov at Virginia Tech University. The comparison study performed analysis of *An. gambiae*, *An. arabiensis* genomes from the same source, where *An. gambiae* represents a complete genome,

Table 4
Statistics on the number of fragments and coverage (in parenthesis) after removing all repeats of length at least *L* in the each of the six mammalian genomes, except *dog*.The column *Orth* accounts the fragments that contain at least one gene. Column *IDOrth* accounts for fragments that contain at least one non-duplicated gene. Similarly, column *UOrth* accounts for fragments that contain at least one gene present in every genome exactly once.

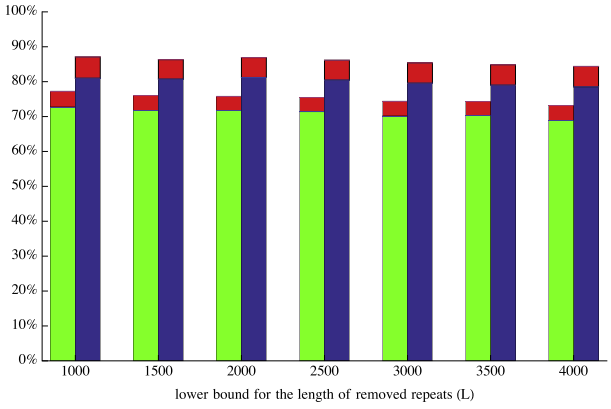
L	Chimpanzee			Dog	Human			Macaca			Mouse			Rat		
	Orth	IDOrth	UOrth		Orth	IDOrth	UOrth	Orth	IDOrth	UOrth	Orth	IDOrth	UOrth	Orth	IDOrth	UOrth
1K	10613	6223	1728	40	20381	5528	1871	1055	5334	1766	12975	4283	1676	10399	4988	1538
	(26.1%)	(19.6%)	(8.1%)	(100%)	(36.9%)	(15.9%)	(7.4%)	(33.2%)	(22.8%)	(10.1%)	(38.3%)	(21.0%)	(10.5%)	(34.9%)	(27.3%)	(10.4%)
1.5K	8994	5572	2015	40	16835	5252	2221	8586	4878	2013	11088	3988	1937	8742	4230	1728
	(39.1%)	(30.2%)	(16.1%)	(100%)	(49.8%)	(25.4%)	(14.5%)	(47.8%)	(35.8%)	(20.1%)	(49.6%)	(30.4%)	(18.7%)	(46.4%)	(37.5%)	(21.5%)
2K	7469	4778	2078	40	13797	4767	2312	6865	4209	2034	9845	3691	2113	7527	3671	1805
	(48.5%)	(38.8%)	(24.3%)	(100%)	(60.6%)	(34.5%)	(22.4%)	(60.8%)	(48.5%)	(31.2%)	(56.5%)	(36.1%)	(25.7%)	(54.1%)	(44.1%)	(29.2%)
2.5K	6497	4262	2092	40	11727	4424	2361	5385	3460	1891	9061	3525	2232	6651	3260	1796
	(55.9%)	(45.5%)	(30.9%)	(100%)	(67.6%)	(41.2%)	(28.6%)	(71.9%)	(59.2%)	(42.2%)	(60.5%)	(39.5%)	(30.4%)	(59.7%)	(49.1%)	(35.4%)
3K	5789	3897	2050	40	10226	4120	2340	4723	2893	1712	8448	3363	2236	5997	2990	1762
	(69.9%)	(54.6%)	(39.3%)	(100%)	(72.3%)	(45.9%)	(33.4%)	(79.3%)	(67.5%)	(51.1%)	(63.6%)	(42.1%)	(33.4%)	(63.9%)	(52.4%)	(39.9%)
3.5K	5197	3588	1996	40	9005	3875	2307	3368	2376	1509	7909	3201	2215	5350	2723	1690
	(69.2%)	(58.6%)	(43.8%)	(100%)	(75.9%)	(50.3%)	(37.8%)	(84.9%)	(75.4%)	(59.1%)	(66.2%)	(44.3%)	(36.1%)	(67.9%)	(55.7%)	(44.2%)
4K	4694	3291	1919	40	8007	3630	2249	2635	1940	1298	7538	3122	2247	4779	2501	1625
	(73.6%)	(63.1%)	(48.3%)	(100%)	(79.2%)	(54%)	(41.5%)	(89.3%)	(80%)	(66.2%)	(68.3%)	(45.9%)	(38.4%)	(71.7%)	(58.9%)	(48.1%)



(a) Evaluation of the assembly results in the experiment, where all genomes are fragmented.



(b) Evaluation of the assembly results in the experiment, where all, but one genome (dog) are fragmented.



(c) Evaluation of the assembly results in the experiment, where only one genome (dog) is fragmented.

Fig. 7. Accuracy of the proposed algorithm on artificially fragmented six mammalian genomes, that were broken at the positions of repeats of length at least *L*, with (blue bars) and without (green bars) integration with MGRA. For each value of *L* (with step 500 bp) blue and green bars give the *true positive* rate, while red bars give *false positive* rate for assembly results. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

while *An. arabiensis* exposes rather high fragmentation. The genome data preparation was similar to ours. The relationships between these genes and their order on scaffold were visualized in genoPlotR Guy et al. (2010) and further compared to the cytogenetic Holt et al. (2002) and physical George et al. (2010) maps identifying breakpoints of fixed reversals. The *An. gambiae* genome assembly was used as a reference for scaffolding in *An. arabiensis*.

Among 10 assemblies in *An. arabiensis* genome identified by our algorithm, the comparison study was able to identify and confirm 6. For example, our algorithm suggested assembly of scaffolds

Table 5
Statistics on the number of fragments and coverage (in parenthesis) after removing all repeats of length at least *L* in the *dog* genome.The column *Orth* accounts the fragments that contain at least one gene. Column *IDOrth* accounts for fragments that contain at least one non-duplicated gene. Similarly, column *UOrth* accounts for fragments that contain at least one gene present in every genome exactly once.

L	Chimpanzee	Dog			Human	Macaca	Mouse	Rat
		Orth	IDOrth	UOrth				
1K	26 (100%)	9067 (33.3%)	4675 (23.7%)	3933 (21.4%)	24 (100%)	22 (100%)	21 (100%)	22 (100%)
1.5K	26 (100%)	7150 (52.1%)	3990 (40.1%)	3480 (37.4%)	24 (100%)	22 (100%)	21 (100%)	22 (100%)
2K	26 (100%)	5579 (65.9%)	3265 (53.4%)	2886 (50.4%)	24 (100%)	22 (100%)	21 (100%)	22 (100%)
2.5K	26 (100%)	4389 (75.8%)	2628 (63.8%)	2346 (60.9%)	24 (100%)	22 (100%)	21 (100%)	22 (100%)
3K	26 (100%)	3605 (81.9%)	2228 (70.7%)	2013 (68.1%)	24 (100%)	22 (100%)	21 (100%)	22 (100%)
3.5K	26 (100%)	3071 (85.6%)	1896 (74.5%)	1717 (72.3%)	24 (100%)	22 (100%)	21 (100%)	22 (100%)
4K	26 (100%)	2683 (88.4%)	1687 (77.9%)	1533 (75.8%)	24 (100%)	22 (100%)	21 (100%)	22 (100%)

Fig. 8. genoPlotR visualization of gene order on scaffolds KB704374, KB704562, KB704518, and KB704685 for *A. arabiensis* genome. Courtesy of Dr. Igor Sharakhov.

KB704562 and KB704374 as well as of scaffolds KB704518 and KB704685 in the *A. arabiensis* genome, which was also identified by the comparison study with the gene reference-based (Fig. 8).

4. Conclusions

In current study, we proposed a scaffold assembly algorithm based on the genome rearrangement analysis, which can be used to assemble highly fragment genomes. The proposed algorithm relies on the properties of breakpoint graph of multiple genomes and can be further integrated with the MGRA framework. We evaluated the proposed algorithm by testing it on both real and simulated genomic data. In both cases, it significantly reduced fragmentation of the genomes and demonstrated high reliability.

While the proposed algorithm relies on unique gene content, we are currently expanding the algorithm with support of non-unique (inserted/deleted or duplicated) genes, which will potentially lead to even better quantity and quality of the scaffold assembly results. We implemented the proposed algorithm in a prototype software, which we plan to make user-friendly and publicly available in near future.

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Appendix A. Anopheles Genomes Cluster Consortium

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